

```
// This program is part of the microstill project.
// For details and instructions visit <http://www.microstill.net>.
//
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#include <OneWire.h>
#include <Bounce2.h>

// pump relais
const int pump=9;

// pump status, 0 for off, >0 for on
int pumpstate = 0;

// heater relais
const int heater=10;

// heater status, 0 for off, > 0 for on
int heaterstate = 0;

// green switch
const int Tastgruen=3;

// green LED
const int LEDgruen=2;

// yellow switch
const int Tastgelb=5;

// yellow LED
const int LEDgelb=4;

// red switch
const int Tastrot=7;

// red LED
const int LEDrot=6;
```

```
// baud rate
int datarate = 9600;

// temperature sensors
OneWire myds(8);

// leakSensor
const int leakSensor = 11;
int blink = 0;

// bouncer for each switch
Bounce bouncer_rot = Bounce();
Bounce bouncer_gelb = Bounce();
Bounce bouncer_gruen = Bounce();

// Variables
// C - Cooler, H - Heater
double SetpointH, MaxTempC, CurrentTempH, CurrentTempC;
unsigned long now, pumpstarttime, HeatStartTime, blinkTime;

// temperature sensor cooler
byte dsaddrC[8];

// temperature sensor heater
byte dsaddrH[8];

// current program: 0, stop; 1, clean; 2, run; 3, leak
int program = 0;

// temperature sensor read stage
int readstage = 0;

void setup() {
  // setup pin modes
  pinMode(LEDgruen, OUTPUT);
  pinMode(LEDgelb, OUTPUT);
  pinMode(LEDrot, OUTPUT);
  pinMode(heater, OUTPUT);
  pinMode(pump, OUTPUT);
  pinMode(Tastrot, INPUT_PULLUP);
  pinMode(Tastgelb, INPUT_PULLUP);
  pinMode(Tastgruen, INPUT_PULLUP);
  pinMode(leakSensor, INPUT_PULLUP);

  // setup bouncer
  bouncer_rot.attach(Tastrot);
```

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bouncer_gelb.attach(Tastgelb);
bouncer_gruen.attach(Tastgruen);

// setup bouncer sensitivity
bouncer_rot.interval(2);
bouncer_gelb.interval(2);
bouncer_gruen.interval(2);

// start serial
Serial.begin(datarate);

// switch off heater and pump
digitalWrite(heater, LOW);
digitalWrite(pump, LOW);

// Set configuration temperature sensors
myds.reset();
myds.write(0xCC); // Skip ROM
myds.write(0x4E); // Write scratch pad
myds.write(0); // TL
myds.write(0); // TH
myds.write(0x3F); // Configuration Register to 10 bit resolution

// address temperature sensor heater
dsaddrH[0] = 0x28;
dsaddrH[1] = 0xFF;
dsaddrH[2] = 0x7C;
dsaddrH[3] = 0xDE;
dsaddrH[4] = 0x37;
dsaddrH[5] = 0x16;
dsaddrH[6] = 0x4;
dsaddrH[7] = 0x93;

// address temperature sensor cooler
dsaddrC[0] = 0x28;
dsaddrC[1] = 0xFF;
dsaddrC[2] = 0x12;
dsaddrC[3] = 0xA6;
dsaddrC[4] = 0x37;
dsaddrC[5] = 0x16;
dsaddrC[6] = 0x4;
dsaddrC[7] = 0x94;
}

void loop() {
// read switches
bouncer_rot.update();
bouncer_gelb.update();
bouncer_gruen.update();

```

```
// switch to respective program
if(bouncer_gruen.read() == LOW) {program = 2;} // run
if(bouncer_gelb.read() == LOW) {program = 1;} // clean
if(bouncer_rot.read() == LOW) {program = 0;} // stop
if(digitalRead(leakSensor) == LOW) {program = 3;} // leak
```

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//*****
```

```
// program STOP
```

```
//*****
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```
if (program == 0) {
    // switch on red LED, others off
    digitalWrite(LEDrot, HIGH);
    digitalWrite(LEDgelb, LOW);
    digitalWrite(LEDgruen, LOW);
    // turn off heater
    digitalWrite(heater,LOW);
    heaterstate = 0;
    // switch off pump
    digitalWrite(pump,LOW);
    pumpstate = 0;
} // end program STOP
```

```
//*****
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```
// program CLEAN
```

```
//*****
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if (program == 1) {
    // update variable now
    now = millis();
    // switch on yellow LED
    digitalWrite(LEDrot, LOW);
    digitalWrite(LEDgelb, HIGH);
    digitalWrite(LEDgruen, LOW);
```

```
// turn off heater
    digitalWrite(heater,LOW);
    heaterstate = 0;
```

```
// initial switch on
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```
if (pumpstate == 0) {
    // switch on pump
    digitalWrite(pump,HIGH);
    // record time pump was started
    pumpstarttime = millis();
    // record pump was started
    pumpstate ++;
}
```

```

// pump is allowed 2 minute work followed by 1 minute break
// run pump for 1 minute then switch off pump
if (now > (pumpstarttime + 60000) && pumpstate > 0) {
    // switch off pump
    digitalWrite(pump, LOW);
}

// wait another 30 seconds then switch to program STOP
if (now > (pumpstarttime + 90000) && pumpstate > 0) {
    // switch to program STOP
    pumpstate = 0;
    program = 0;
}
} // end program CLEAN

//*****
// program RUN
//*****
if (program == 2) {
    // switch on green LED
    digitalWrite(LEDrot, LOW);
    digitalWrite(LEDgelb, LOW);
    digitalWrite(LEDgruen, HIGH);
    // define set point for heater
    SetpointH = 100;
    // define max temperature of cooler
    MaxTempC = 80;
}

if (program == 2) {

// start measurement and conversion
if (readstage == 0) {
myds.reset();
myds.write(0xCC); // Skip ROM
myds.write(0x44); // start conversion
readstage++;
// switch off pump
digitalWrite(pump, LOW);
}

// read temperature after conversion is ready, i.e. myds.read() > 0
if (myds.read() && readstage) {
CurrentTempC = dsreadtemp(myds, dsaddrC, 10);
CurrentTempH = dsreadtemp(myds, dsaddrH, 10);
now = millis();
}
}

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// start heat pulse if temperature below target
if (CurrentTempH < SetpointH + 10 && heaterstate == 0) {
    // switch on heater
    heaterstate++;
    digitalWrite(heater,HIGH);
    HeatStartTime = millis();
// print current temperatures
    Serial.print("Heater ON at: ");
    Serial.print(HeatStartTime);
    Serial.print(" ms Temp Heater: ");
    Serial.print(CurrentTempH);
    Serial.print(" C Temp Cooler: ");
    Serial.print(CurrentTempC);
    Serial.println(" C");
}

// turn off heater after 1 sec
if (now > (1000 + HeatStartTime) && heaterstate > 0) {
    // switch off heater
    digitalWrite(heater,LOW);
}

// wait 1 more second before allowing next heat pulse
if (now > (2000 + HeatStartTime) && heaterstate > 0) {
    // heater status
    heaterstate = 0;
}

// switch on pump for 40 ms then pause for 960 ms
if (now > (1000 + pumpstarttime) && CurrentTempH > SetpointH)
{
    // record time of pump run
    pumpstarttime = now;
    // switch on pump for 40 ms
    digitalWrite(pump,HIGH); // is on
    delay(40); // 40 ms pause
        // extent pause to 240 ms if cooler temperature is too high
        if (CurrentTempC > MaxTempC) {delay(200);}
    digitalWrite(pump,LOW); // is off
}

// get new temperature reading
readstage = 0;
} // end read temperature

} // end programm == 2

//*****
// program LEAK

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//*****
if (program == 3) {
    // blink on red LED, others off
    now = millis();
    if (blink = 0) {
        blink++;
        blinkTime = millis();
        digitalWrite(LEDrot, HIGH);
    }
    if (now > (blinkTime + 200) && blink > 0) {
        digitalWrite(LEDrot, LOW);
    }
    if (now > (blinkTime + 400) && blink > 0) {
        blink = 0;
    }
    digitalWrite(LEDgelb, LOW);
    digitalWrite(LEDgruen, LOW);
    // turn off heater
    digitalWrite(heater, LOW);
    heaterstate = 0;
    // switch off pump
    digitalWrite(pump, LOW);
    pumpstate = 0;
} // end program LEAK
}

float dsreadtemp(OneWire myds, byte addr[8], byte resolution) {
byte present = 0;
int i;
byte data[12];
byte type_s;
float celsius;

// identify temperature sensor
switch (addr[0]) {
case 0x10:
// DS18S20
type_s = 1;
break;
case 0x28:
// DS18B20
type_s = 0;
break;
case 0x22:
// DS1822
type_s = 0;
break;
default:

```

```
Serial.println(F("Device is not a DS18x20 family device."));
}

present = myds.reset();
myds.select(addr);
myds.write(0xBE); // Read Scratchpad
for ( i = 0; i < 9; i++) { // we need 9 bytes
data[i] = myds.read();
}

// convert the data to actual temperature
unsigned int raw = (data[1] << 8) | data[0];
if (type_s) {
raw = raw << 3; // 9 bit resolution default
if (data[7] == 0x10) {
// count remain gives full 12 bit resolution
raw = (raw & 0xFFF0) + 12 - data[6];
} else {
byte cfg = (data[4] & 0x60);
if (cfg == 0x00) raw = raw << 3; // 9 bit resolution
else if (cfg == 0x20) raw = raw << 2; // 10 bit resolution
else if (cfg == 0x40) raw = raw << 1; // 11 bit resolution
}
}
celsius = (float)raw / 16.0;
return celsius;
}
```